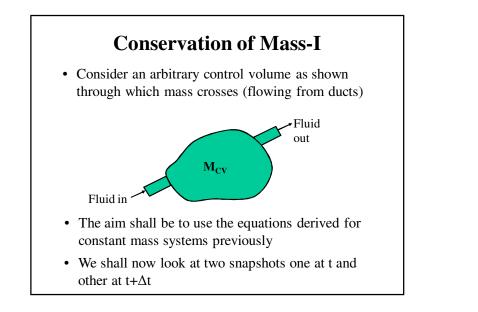
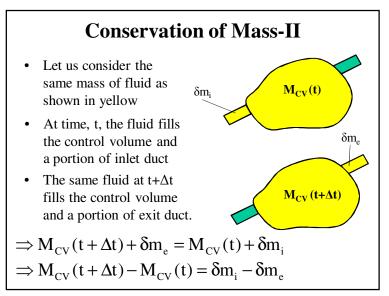


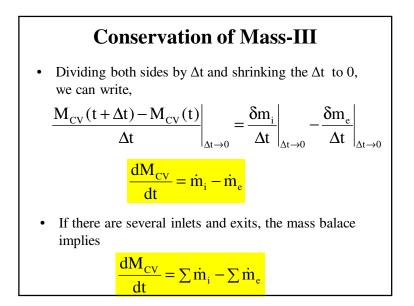
# **Analysis of Open Systems**

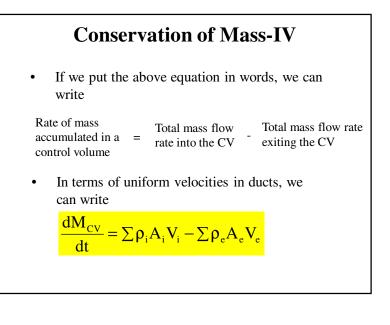
- Our previous discussions were focussing on closed system generally confined to a chamber with rigid walls or piston cylinder where a fixed mass of fluid trapped.
- Many engineering systems have fluid flowing through them and the mass of fluid inside the device need not be constant
- Systems through which mass passes by are called open systems and we shall derive the governing relations. This kind of analysis is also called control volume analysis
- We will show later that the two forms are equivalent. However, one form makes the problem easier to solve.

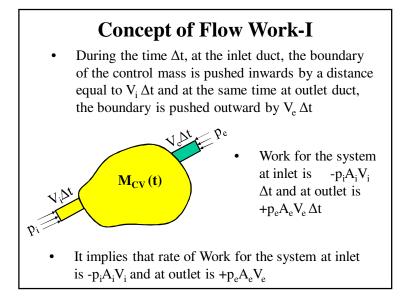




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# Concept of Flow Work-II

• Or the same can respectively be written as

$$\begin{aligned} & -\frac{p_i}{\rho_i} \dot{m}_i \text{ and } \frac{p_e}{\rho_e} \dot{m}_e \\ & \text{Or } -p_i v_i \dot{m}_i \text{ and } p_e v_e \dot{m}_e \end{aligned}$$

• Thus the rate of work for the control volume at inlet and outlet are respectively  $-p_i v_i \dot{m}_i$  and  $p_e v_e \dot{m}_e$ 

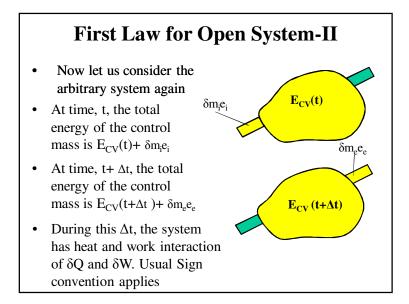
### First Law for Open System-I

- We can now derive the first law for open system.
- Let the kinetic, potential and internal energy per unit mass be denoted by V<sup>2</sup>/2, u, gz. Collectively they can be clubbed together at inlet as

$$e_i = u_i + \frac{V_i^2}{2} + gz_i$$

• The same at outlet shall be

$$e_{e} = u_{e} + \frac{V_{e}^{2}}{2} + gz_{e}$$



#### First Law for Open System-III

• The first law for the control mass can be written as,

 $E_{CV}(t+\Delta t) + \delta m_e e_e$ -  $(E_{CV}(t) + \delta m_i e_i) = \delta Q - \delta W$ 

• Rearranging and dividing both sides by  $\Delta t$  and shrinking the  $\Delta t$  to 0, we can write,

$$\frac{\mathbf{E}_{CV}(t + \Delta t) - \mathbf{E}_{CV}(t)}{\Delta t} \Big|_{\Delta t \to 0} = \frac{\delta \mathbf{Q}}{\Delta t} \Big|_{\Delta t \to 0} - \frac{\delta \mathbf{W}}{\Delta t} \Big|_{\Delta t \to 0} + \mathbf{e}_{i} \frac{\delta \mathbf{m}_{i}}{\Delta t} \Big|_{\Delta t \to 0} - \mathbf{e}_{e} \frac{\delta \mathbf{m}_{e}}{\Delta t} \Big|_{\Delta t \to 0}$$
  
or, 
$$\frac{d\mathbf{E}_{CV}}{dt} = \dot{\mathbf{Q}}_{CV} - \dot{\mathbf{W}} + \dot{\mathbf{m}}_{i} \mathbf{e}_{i} - \dot{\mathbf{m}}_{e} \mathbf{e}_{e}$$

#### First Law for Open System-IV

• Splitting the flow work out of W<sub>CV</sub> and accounting it separately

$$\dot{\mathbf{W}} = \dot{\mathbf{W}}_{Flow work} + \dot{\mathbf{W}}_{CV}$$

$$= -p_{i}v_{i}\dot{\mathbf{m}}_{i} + p_{i}v_{i}\dot{\mathbf{m}}_{i} + \dot{\mathbf{W}}_{CV}$$

$$\therefore \frac{dE_{CV}}{dt} = \dot{\mathbf{Q}}_{CV} - \dot{\mathbf{W}}_{CV} + \dot{\mathbf{m}}_{i}(\mathbf{e}_{i} + p_{i}v_{i}) - \dot{\mathbf{m}}_{e}(\mathbf{e}_{e} + p_{e}v_{e})$$

$$\dot{\mathbf{E}}_{CV} = \dot{\mathbf{Q}}_{CV} - \dot{\mathbf{W}}_{CV} + \dot{\mathbf{m}}_{i}\left(\mathbf{u}_{i} + \frac{V_{i}^{2}}{2} + gz_{i} + p_{i}v_{i}\right)$$

$$- \dot{\mathbf{m}}_{e}\left(\mathbf{u}_{e} + \frac{V_{e}^{2}}{2} + gz_{e} + p_{e}v_{e}\right)$$

## First Law for Open System-V

• For multiple inlets and outlets, we can write,

$$\dot{E}_{CV} = \dot{Q}_{CV} - \dot{W}_{CV} + \sum \dot{m}_i \left( u_i + \frac{V_i^2}{2} + gz_i + p_i v_i \right) - \sum \dot{m}_e \left( u_e + \frac{V_e^2}{2} + gz_e + p_e v_e \right)$$

• Steady state implies that the state of the fluid in Control volume does not change with time

# First Law for Open System-VI • For Steady flow, $\frac{dM_{CV}}{dt} = 0 = \sum \rho_i A_i V_i - \sum \rho_e A_e V_e$ $\implies \sum \dot{m}_i = \sum \dot{m}_e$ • For Single inlet and outlet $\dot{m}_i = \dot{m}_e = \dot{m}$

