

# Gears

ME 423: Machine Design  
Instructor: Ramesh Singh



# Outline

- Types of Gear
- Nomenclature
- Basic Gear Concepts
- Gear Trains



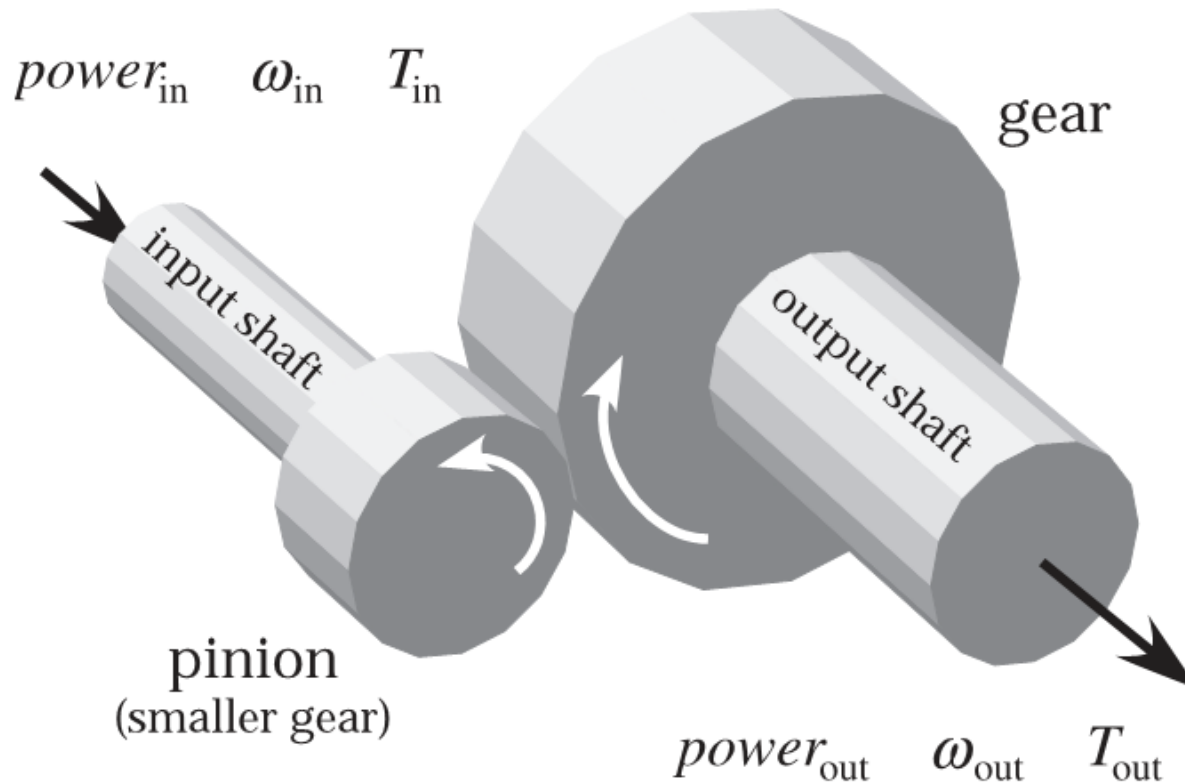
ME 423: Machine Design  
Instructor: Ramesh Singh

# Functions of a Gear

- Power transmission
- Change rotational speed/torque
- Maintain constant speed ratio



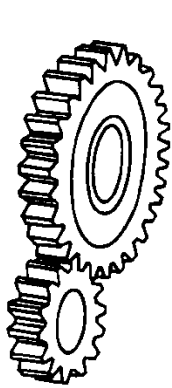
# Gear



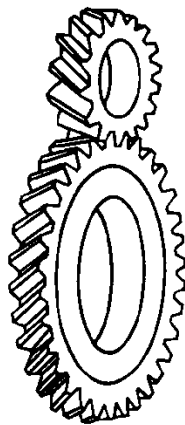
ME 423: Machine Design  
Instructor: Ramesh Singh



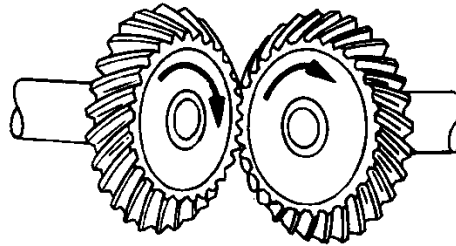
# Types of Gears



SPUR GEAR  
GEARS



HELICAL GEAR

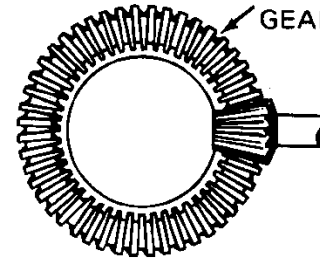


SPIRAL BEVEL GEAR

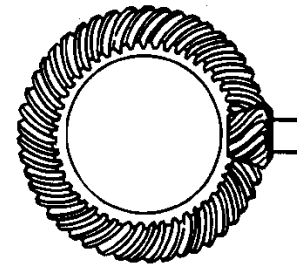


PINION GEAR

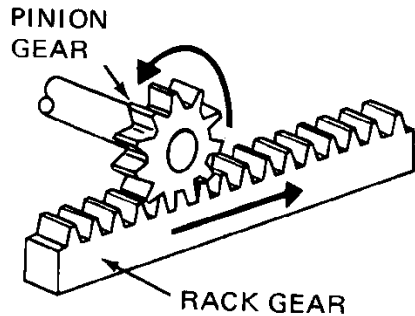
RING GEAR



SPUR BEVEL GEAR

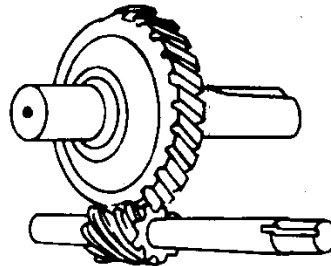


SPIRAL BEVEL GEAR



PINION GEAR

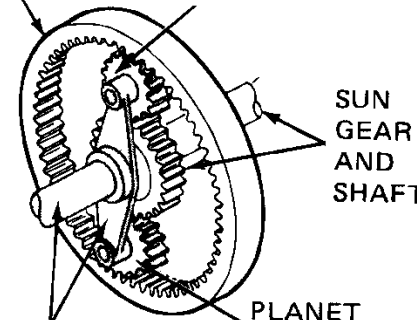
RACK AND-PINION GEAR



WORM GEAR

INTERNAL GEAR

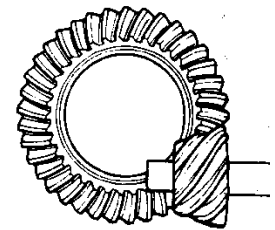
PLANET PINION



SUN GEAR AND SHAFT

PLANET-PINION CARRIER AND SHAFT

PLANET PINION

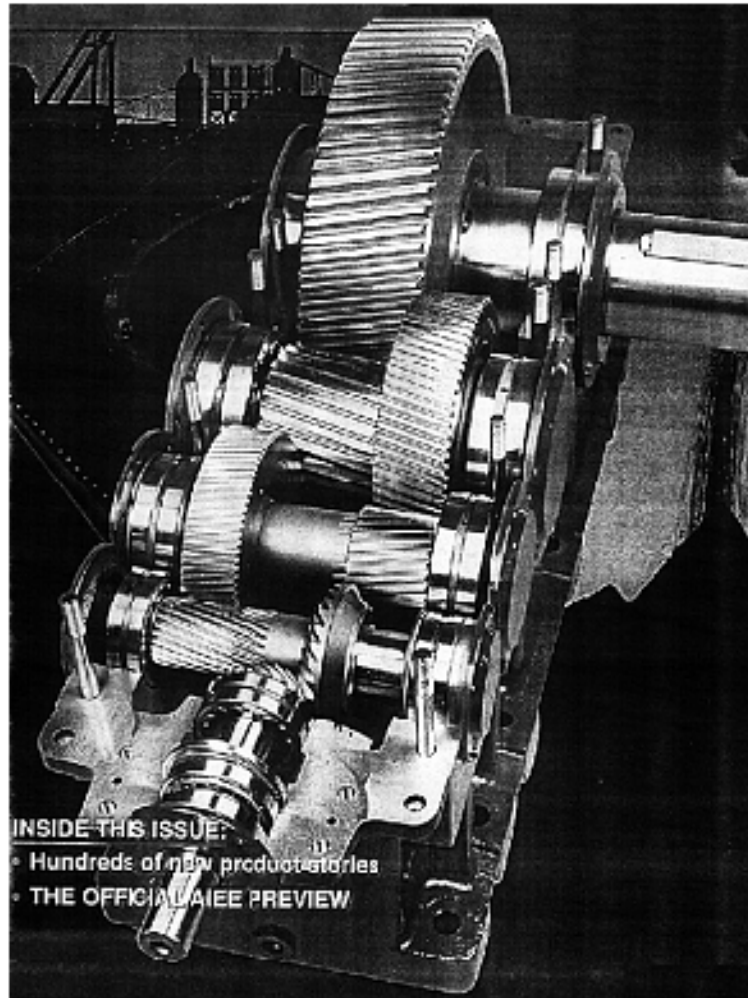


HYPOID GEAR

ME 423: Machine Design  
Instructor: Ramesh Singh



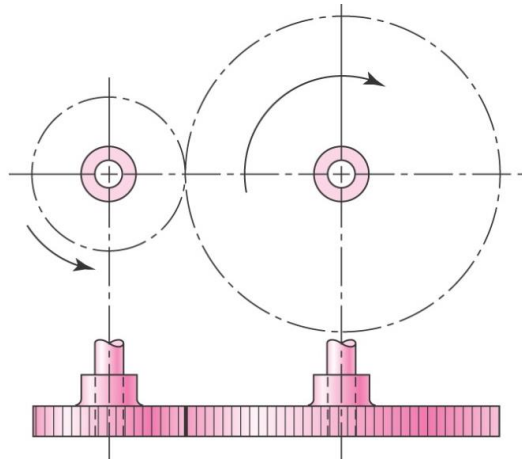
# Gear Box



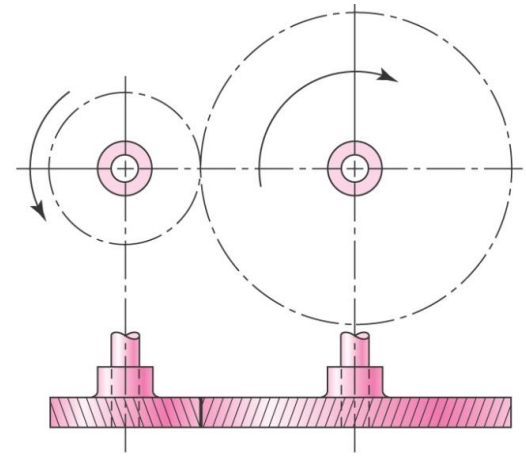
ME 423: Machine Design  
Instructor: Ramesh Singh



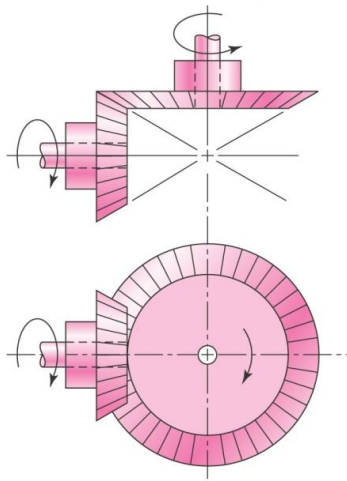
# Type of Gears



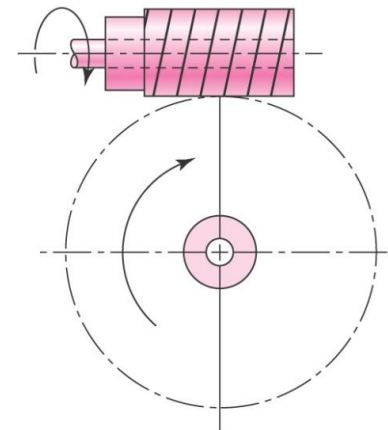
Spur



Helical



Bevel

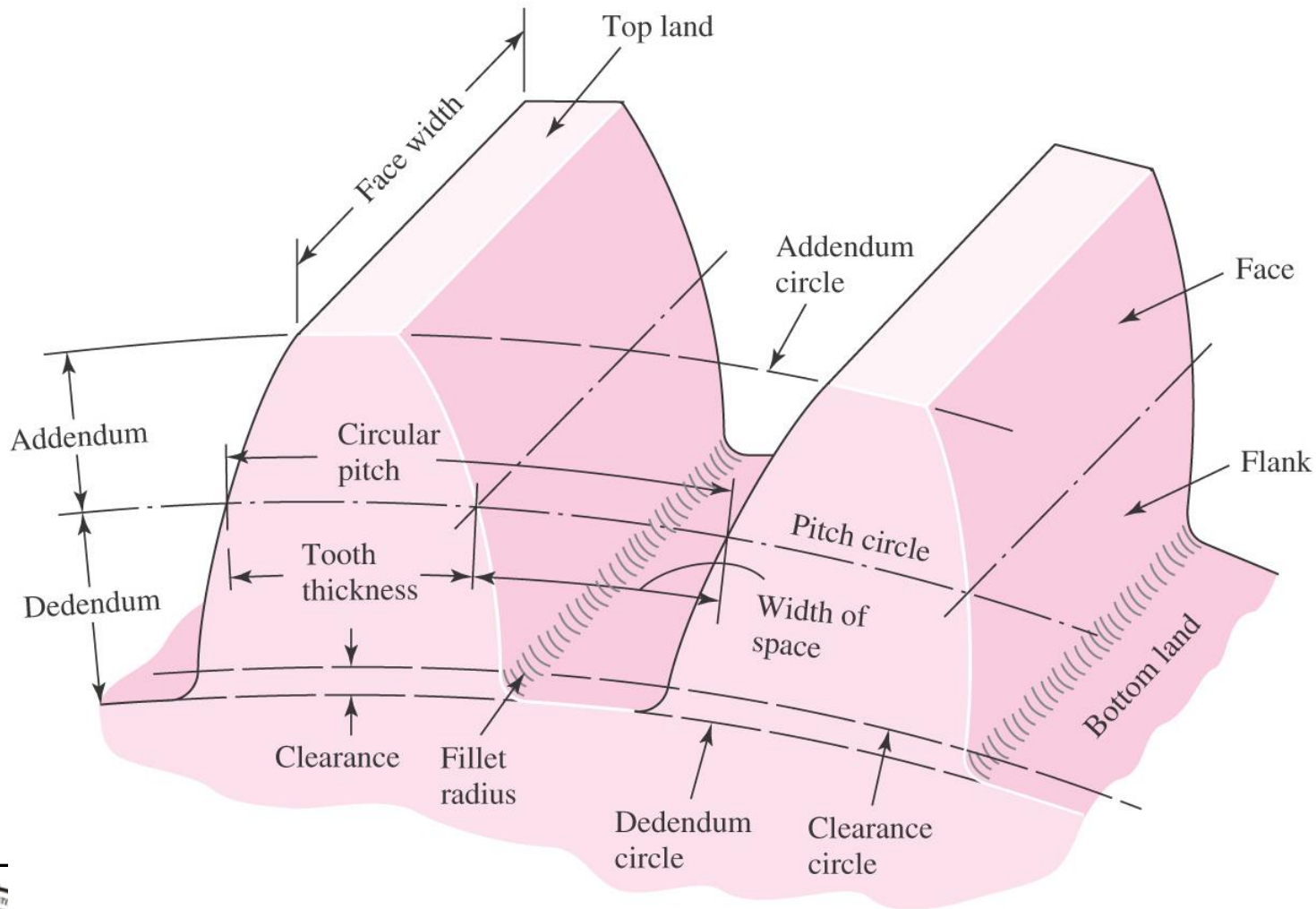


Worm

ME 423: Machine Design  
Instructor: Ramesh Singh



# Nomenclature



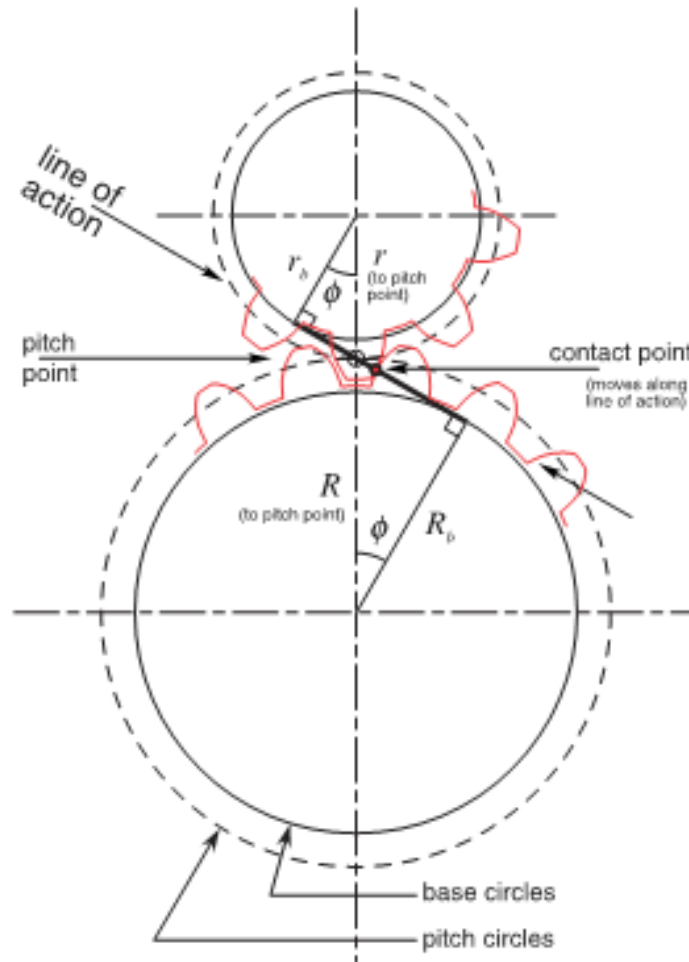
ME 423: Machine Design  
Instructor: Ramesh Singh





# Line of Action

Contact between a meshing pair of gears is arranged to occur purely along a specified "line of action":

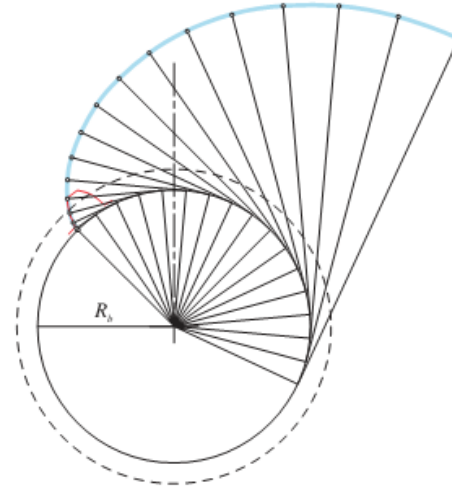


ME 120: Machine Design  
Instructor: Ramesh Singh

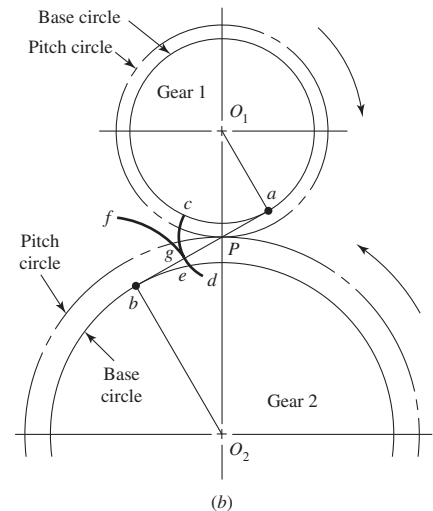


# Involute Profile

- When the tooth profiles are designed so as to produce a constant angular- velocity ratio during meshing, these are said to have conjugate action
- Involute profile is required for conjugate action
- Formed by unwrapping a tangent chord from the base circle



$$V = |r_1\omega_1| = |r_2\omega_2|$$



# Definitions

- Diametral pitch,  $P = N/D$
- Module  $M$  is reciprocal of  $P = D/N$
- Circular pitch =  $\pi M$  (arc on pitch circle from flank of one tooth to other tooth)
- Base pitch =  $P_b = \pi M \cos\phi$  (base circle  $r_b = r \cos\phi$ )
- Addendum =  $M$
- Dedendum =  $1.157 M/1.250M/1.400M$
- Clearance = Dedendum-addendum
- $M, N, \phi$  are required for characterization



# Standardized Tooth Systems

- Common pressure angles  $\phi$ : 20° and 25°
- Older pressure angle: 14 1/2°
- Common face width:

$$3p < F < 5p$$

$$p = \frac{\pi}{P}$$

$$\frac{3\pi}{P} < F < \frac{5\pi}{P}$$

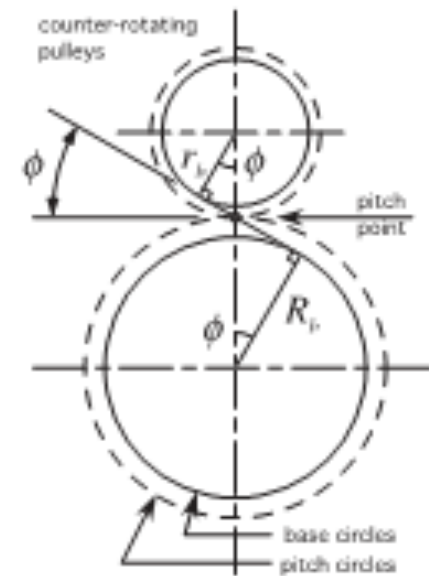
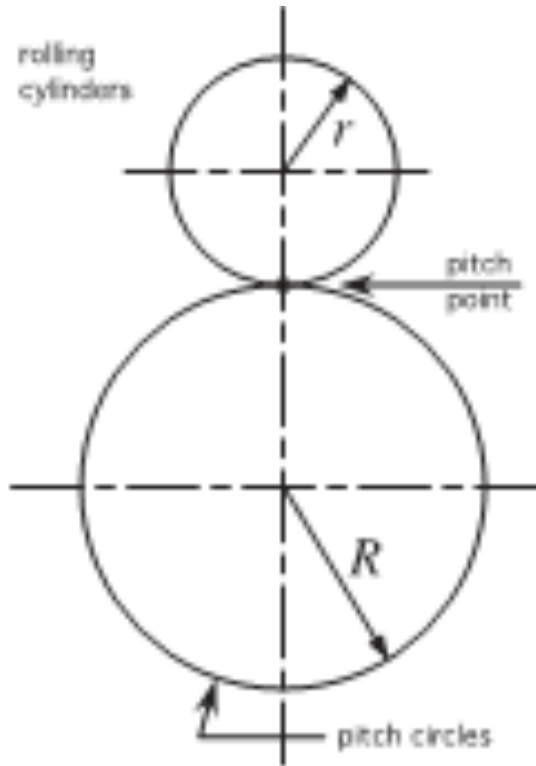
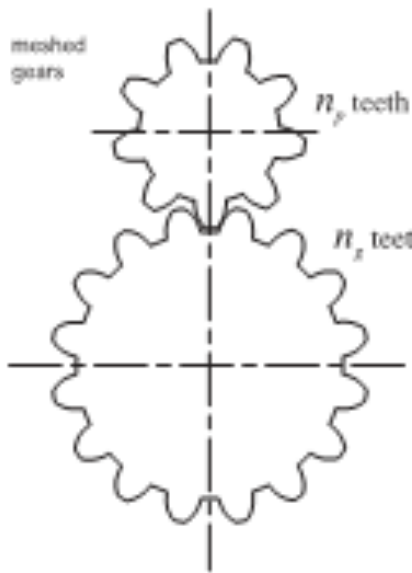


# Fundamental Law of Gearing

- The common normal of the tooth profiles at all points within the mesh must always pass through a fixed point on the line of the centers called pitch point. Then the gearset's velocity ratio will be constant through the mesh and be equal to the ratio of the gear radii.



# Gear Kinematics



The "gear ratio" is:

$$\frac{n_g}{n_p} = \frac{R}{r} = \frac{R_b}{r_b}$$

ME 423: Machine Design  
Instructor: Ramesh Singh



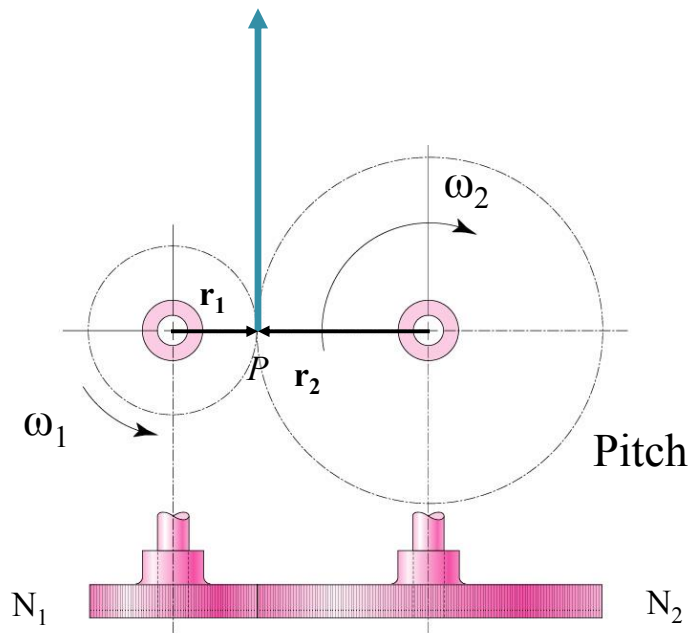
# Gear Ratio

- $V_p$  of both gears is the same at point P, the pitch (circle contact) point
- $V_p = \omega_1 r_1 = \omega_2 r_2$

Gear Ratio  $\geq 1$

$$\frac{\omega_1}{\omega_2} = \frac{r_2}{r_1} = \frac{N_2}{N_1}$$

$\omega_2$  rotates opposite of  $\omega_1$



# Simple Gear Trains

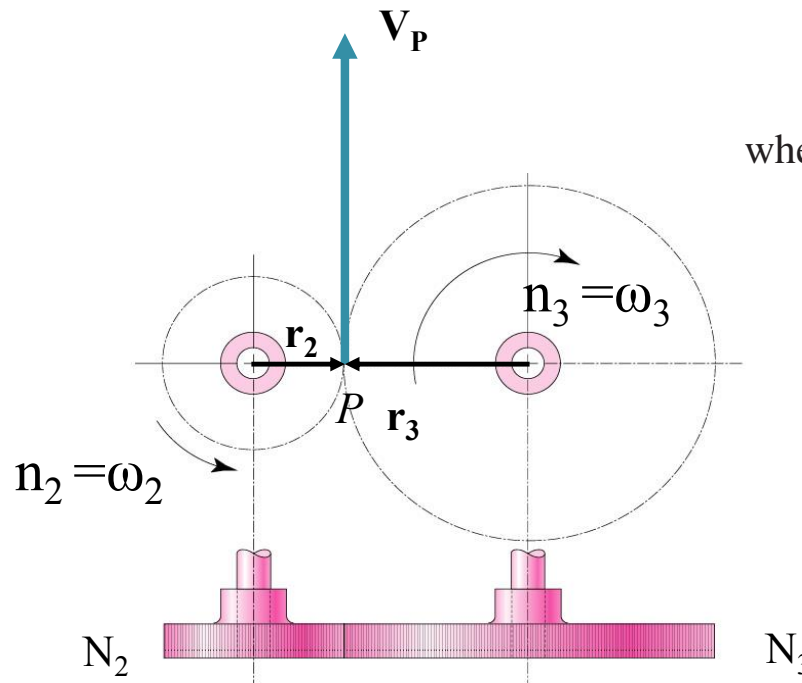
- For a pinion 2 driving a gear 3, the speed of the driven gear is

$$n_3 = \left| \frac{N_2}{N_3} n_2 \right| = \left| \frac{d_2}{d_3} n_2 \right|$$

where  $n$  = revolutions or rev/min

$N$  = number of teeth

$d$  = pitch diameter



ME 423: Machine Design  
Instructor: Ramesh Singh





# Simple Gear Trains

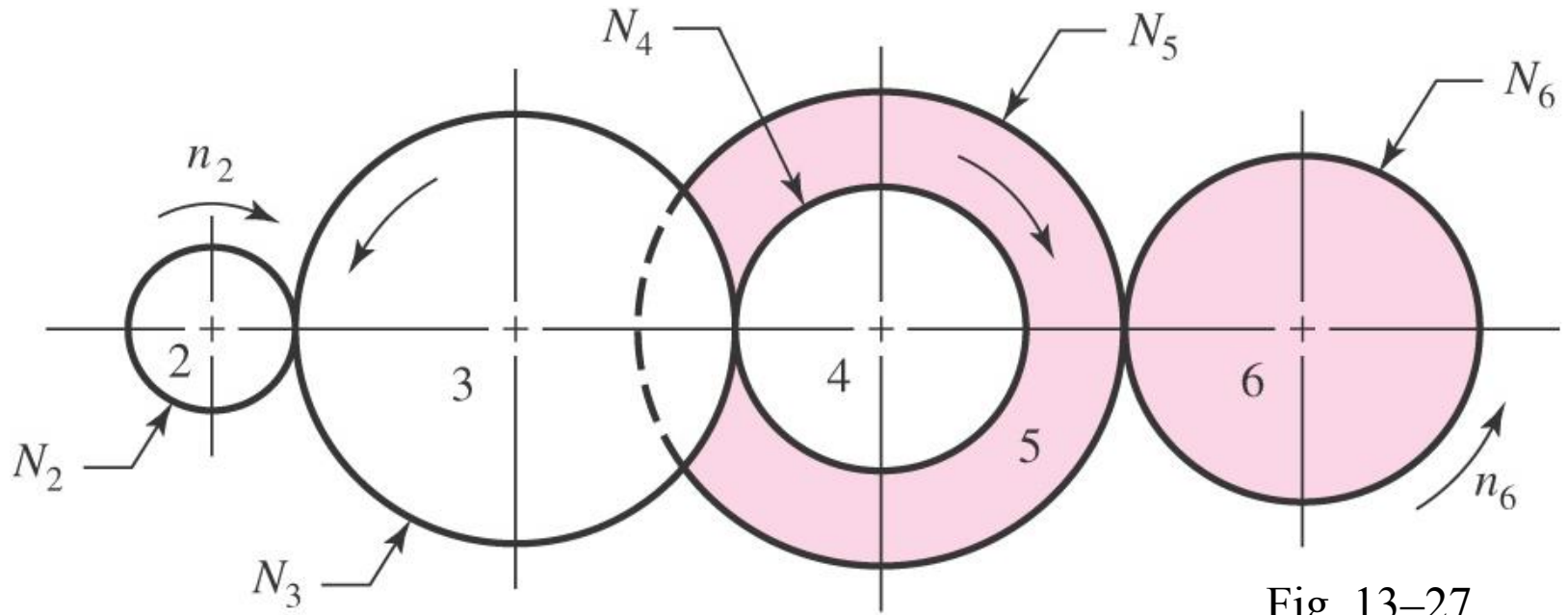


Fig. 13-27

$$n_6 = -\frac{N_2 N_3 N_5}{N_3 N_4 N_6} n_2$$

$$e = \frac{\text{product of driving tooth numbers}}{\text{product of driven tooth numbers}} \quad (13-30)$$

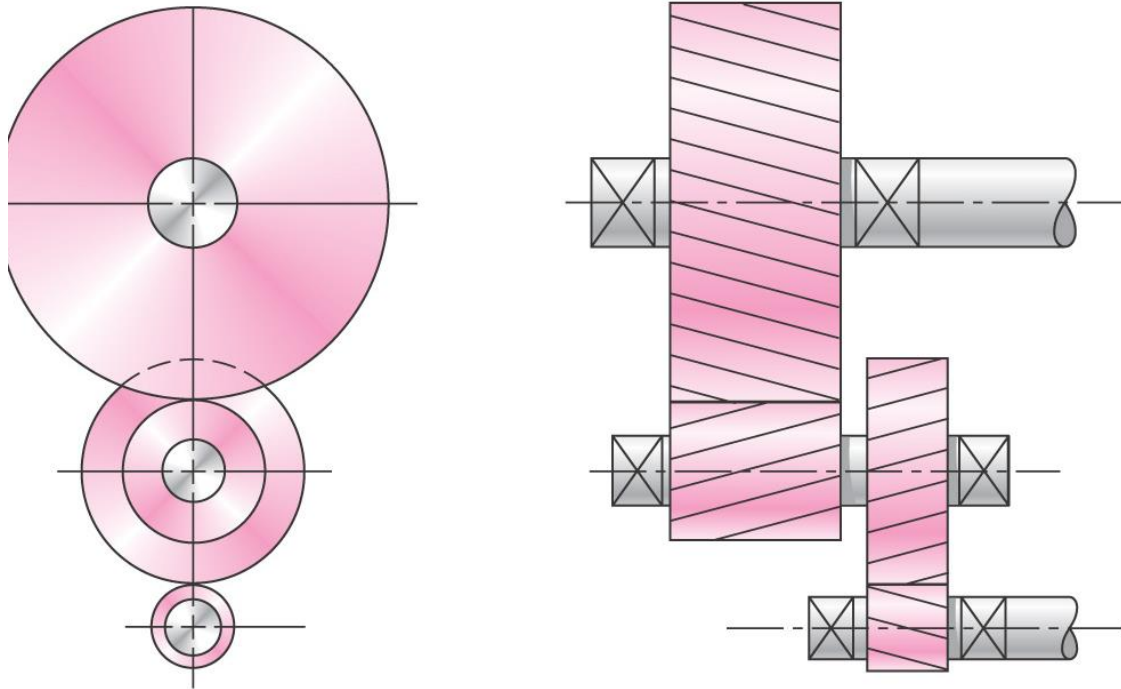
$$n_L = e n_F \quad (13-31)$$

Instructor: Ramesh Singh

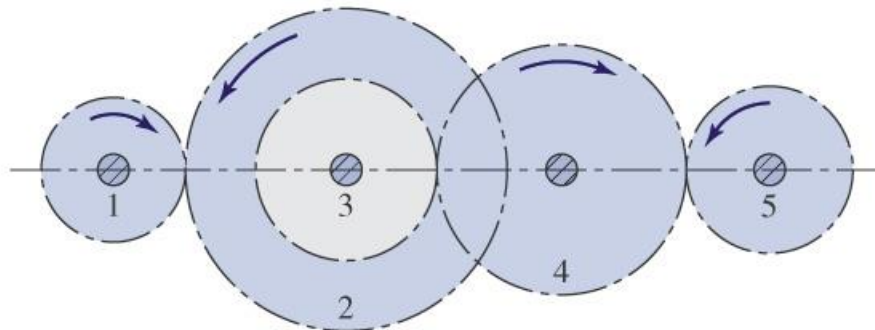
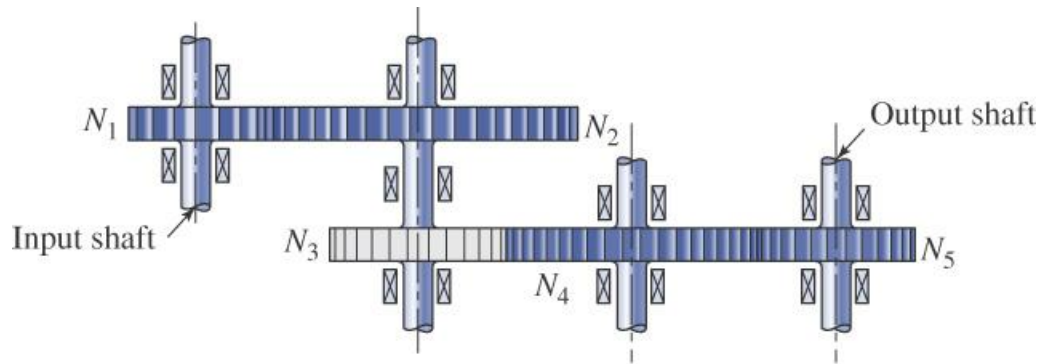


# Gear Trains

- A practical limit on train value for one pair of gears is 10 to 1
- To obtain more, compound two gears onto the same shaft



# Compound Gear Trains



$$\frac{n_5}{n_1} = \left(-\frac{N_1}{N_2}\right)\left(-\frac{N_3}{N_4}\right)\left(-\frac{N_4}{N_5}\right)$$

ME 423: Machine Design  
Instructor: Ramesh Singh



# Example Problem

- A gearset consists of a 16-tooth pinion driving a 40-tooth gear. The diametral pitch is 2, and the addendum and dedendum are  $1/P$  and  $1.25/P$ , respectively. The gears are cut using a pressure angle of 20deg
- (a) Compute the circular pitch, the center distance, and the radii of the base circles. (b) In mounting these gears, the center distance was incorrectly made 1/4 in larger. Compute the new values of the pressure angle and the pitch-circle diameters.



# Solution

Solution

Answer

(a)

$$p = \frac{\pi}{P} = \frac{\pi}{2} = 1.57 \text{ in}$$

The pitch diameters of the pinion and gear are, respectively,

$$d_P = \frac{16}{2} = 8 \text{ in} \quad d_G = \frac{40}{2} = 20 \text{ in}$$

Therefore the center distance is

Answer

$$\frac{d_P + d_G}{2} = \frac{8 + 20}{2} = 14 \text{ in}$$

Since the teeth were cut on the  $20^\circ$  pressure angle, the base-circle radii are found to be, using  $r_b = r \cos \phi$ ,

Answer

$$r_b \text{ (pinion)} = \frac{8}{2} \cos 20^\circ = 3.76 \text{ in}$$

Answer

$$r_b \text{ (gear)} = \frac{20}{2} \cos 20^\circ = 9.40 \text{ in}$$



# Solution

(b) Designating  $d'_P$  and  $d'_G$  as the new pitch-circle diameters, the  $\frac{1}{4}$ -in increase in the center distance requires that

$$\frac{d'_P + d'_G}{2} = 14.250 \quad (1)$$

Also, the velocity ratio does not change, and hence

$$\frac{d'_P}{d'_G} = \frac{16}{40} \quad (2)$$

Solving Eqs. (1) and (2) simultaneously yields

**Answer**  $d'_P = 8.143 \text{ in} \quad d'_G = 20.357 \text{ in}$

Since  $r_b = r \cos \phi$ , the new pressure angle is

**Answer** 
$$\phi' = \cos^{-1} \frac{r_b \text{ (pinion)}}{d'_P/2} = \cos^{-1} \frac{3.76}{8.143/2} = 22.56^\circ$$

