# **ME 216: Engineering Metrology**

### **Fundamentals of Geometric Tolerances**

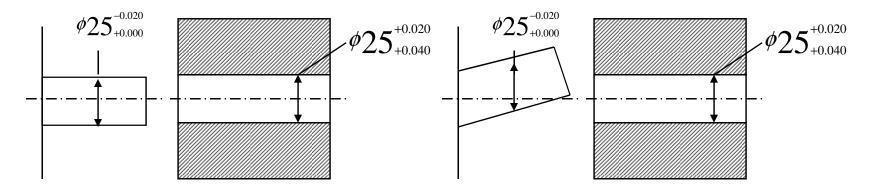
Dr. Suhas S. Joshi, Department of Mechanical Engineering, Indian Institute of Technology, Bombay, Powai, MUMBAI – 400 076 (India) Phone: 91 22 2576 7527 (O) / 2576 8527 ®; ssjoshi@iitb.ac.in

## **Tolerance of Size and Geometry**

The tolerance on 'Size' is also called as 'Dimensional' tolerance.

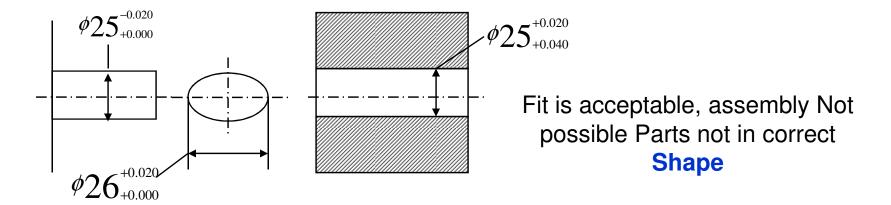
Example -  $\phi_{25_{-0.000}}^{+0.020}$ 

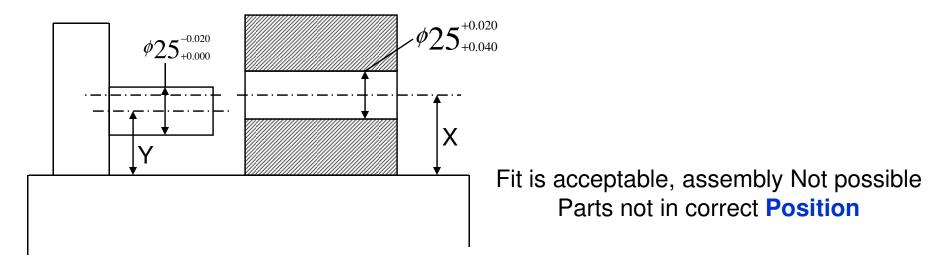
But these tolerances may not be sufficient to manufacture the desired fit perfectly. So we require additional tolerances, called 'Geometrical' Tolerances. Example –



Fit is acceptable, assembly possible Parts in Correct **Orientation**  Fit is acceptable, assembly Not possible Parts not in correct **Orientation** 

### **Tolerance of Size and Geometry**





## **Tolerance of Size and Geometry**

Therefore, in addition to selecting FIT, it is also important that we specify additional tolerances so that the desired FIT is achieved. These types of tolerances which help specify the functional requirements more clearly, are called as 'Geometrical Tolerances'. These are of following three types –

- 1. Tolerances on Shape or Form
- 2. Tolerances on Orientation
- 3. Tolerances on **Position**

Symbol	Tolerance	Reference
	Value	datum

Geometric Tolerance Representation

A. Characteristics of Form/Shape

Sr. No.	Characteristics	Symbol
1.	Straightness	
2.	Flatness	
3.	Circularity	$\bigcirc$
4.	Cylindricity	
5.	Profile of a Line	
6.	Profile of a Surface	

#### **B.** Characteristics of Orientation

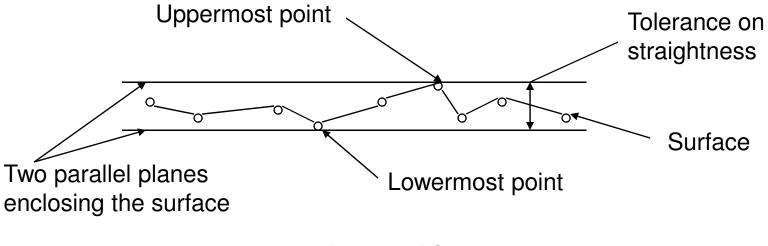
S. N.	Characteristics	Symbol
1.	Parallelism	
2.	Perpendicularity	
3.	Angularity	

#### **C.** Characteristics of Position

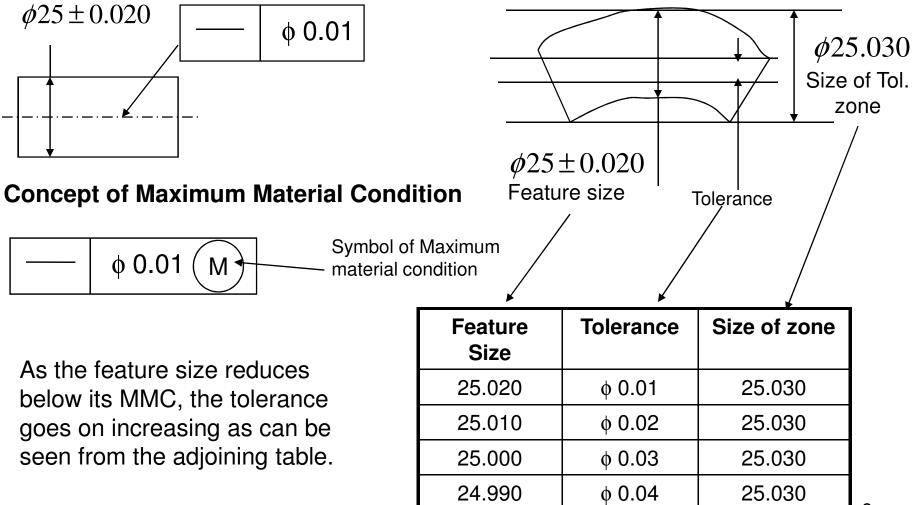
S.N.	Characteristics	Symbol
1.	Position	$\bigcirc$
2.	Concentricity/Co-axiality	$\bigcirc$
3.	Symmetry	
4.	Run out	6

### **Straightness**

It is the characteristic of a line where all the elements of a line are colinear. In general, there could be two lines, within which, all the points on a line lie.



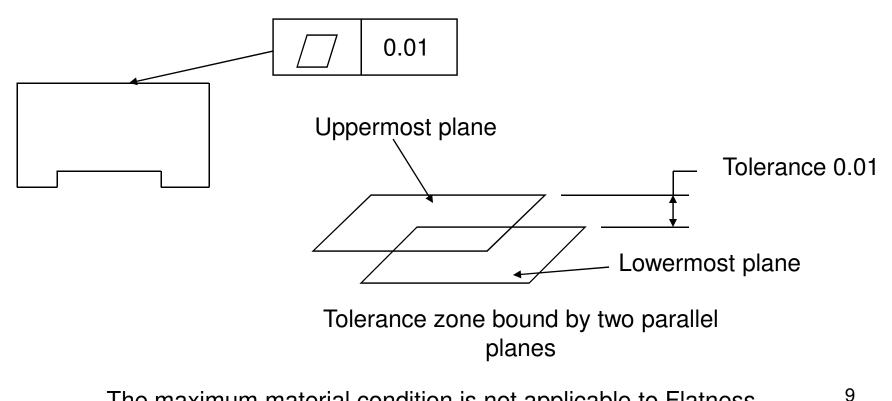
**Definition of Straightness** 



8

### Flatness

It is defined as minimum distance between two planes within which all the points on a surface lie. A surface along which all the points lie along single plane is called as perfectly flat surface.

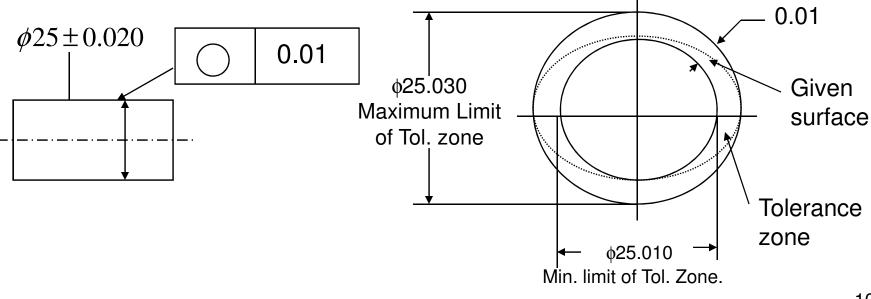


The maximum material condition is not applicable to Flatness

#### Circularity

It is defined for a cylindrical or conical surfaces. It defines the distance between the surface and its axis.

- Ideally, all points on a surface (at a cross-section), should be equidistant from the axis for the cross-section to be perfectly circular.
- The tolerance on circularity is defined by two concentric circles within which a surface can lie. The distance between two the concentric circles is called tolerance.

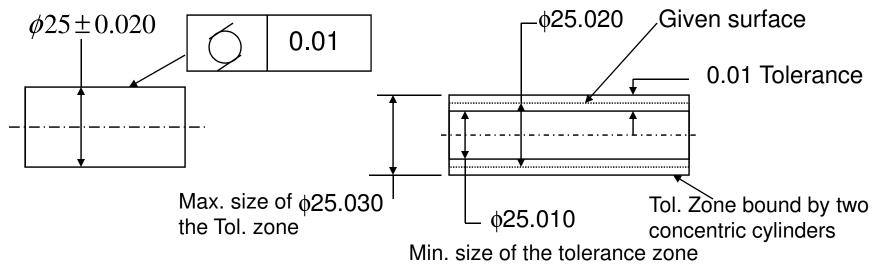


The maximum material condition is not applicable to Circularity

#### Cylindricity

It is defined for a surface of revolution. It defines the distance between the surface and its axis.

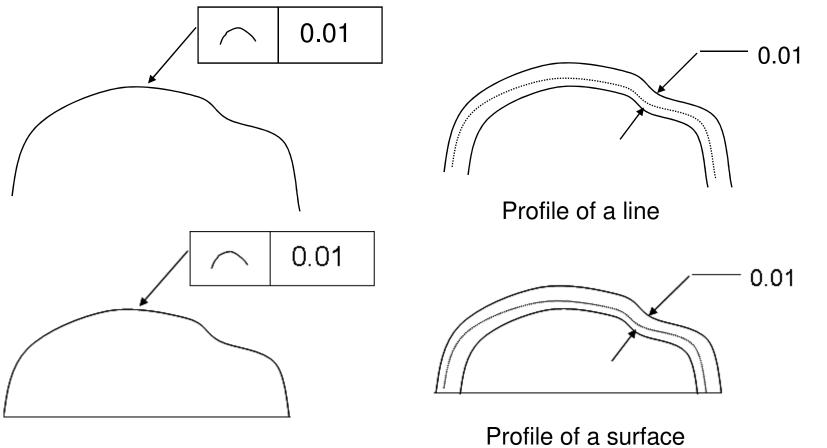
- Ideally, all points on a surface (of revolution), should be equidistant from the axis for the cross-section to be perfectly cylindrical.
- The tolerance on cylindricity is defined by two concentric cylinders within which a surface can lie. The distance between the two concentric cylinders is called tolerance.



The maximum material condition is not applicable to cylindricity <sup>11</sup>

#### **Profile of Line or Surface**

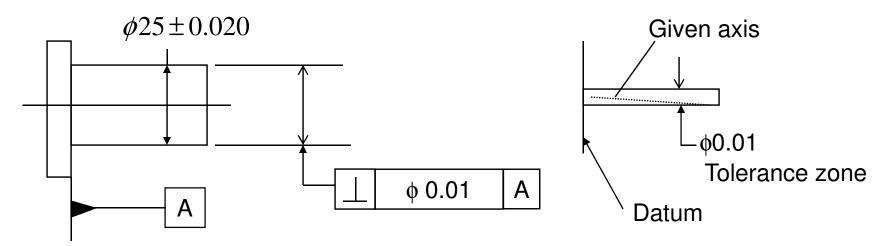
It is defined for a line of any shape of surface of any shape. It defines the distance between two lines or surfaces of the same shape as that of the line or surface in question, separated by a distance equal to tolerance.



#### Perpendicularity

It is defined for a feature (like surface or line) with reference to another feature called reference. It defines the distance between two lines or surfaces that are parallel to each other and perpendicular to the datum surface and encompass the line or surface in question.

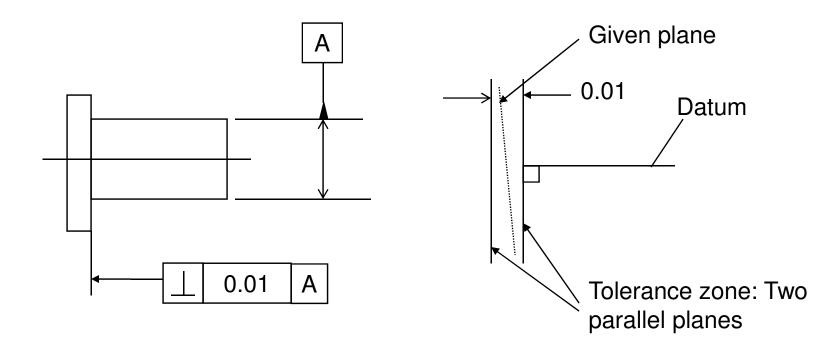
#### Perpendicularity of a Line with Surface as datum



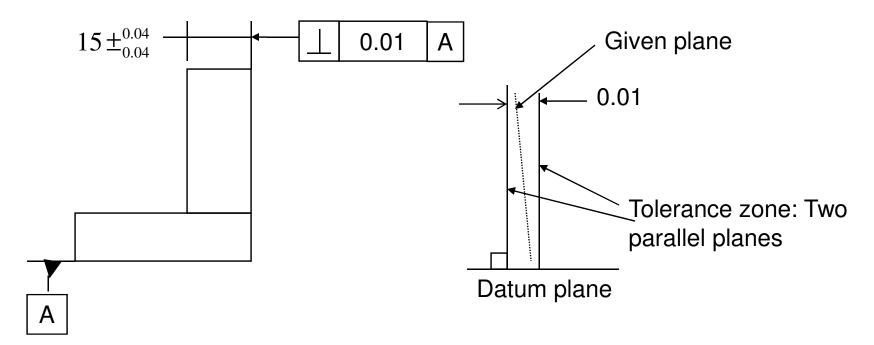
Maximum size of the part = Maximum size permitted by the dimensional tolerance (25.020) + geometrical tolerance (0.01) = 25.03 mm

Minimum size of the part = Minimum size permitted by the dimensional tolerance (24.98) - Geometrical tolerance (0.01) = 24.97 mm

#### Perpendicularity of a Surface with Line as a datum



#### Perpendicularity of a Surface with Surface as a datum



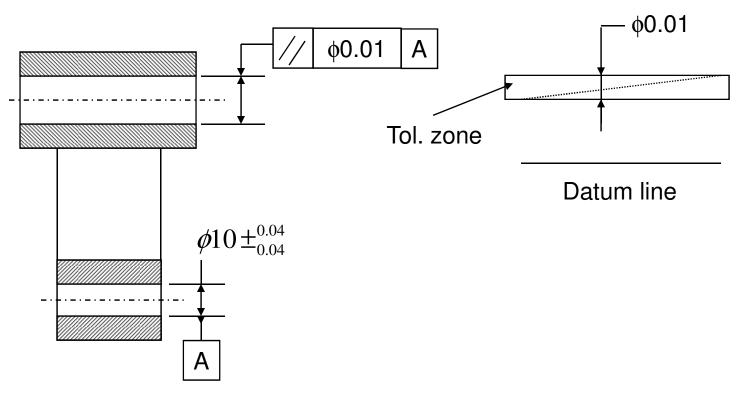
Maximum size of the part = Maximum size permitted by the dimensional tolerance (15.040) + geometrical tolerance (0.01) = 15.05 mm

Minimum size of the part = Minimum size permitted by the dimensional tolerance (14.96) - Geometrical tolerance (0.01) = 14.95 mm

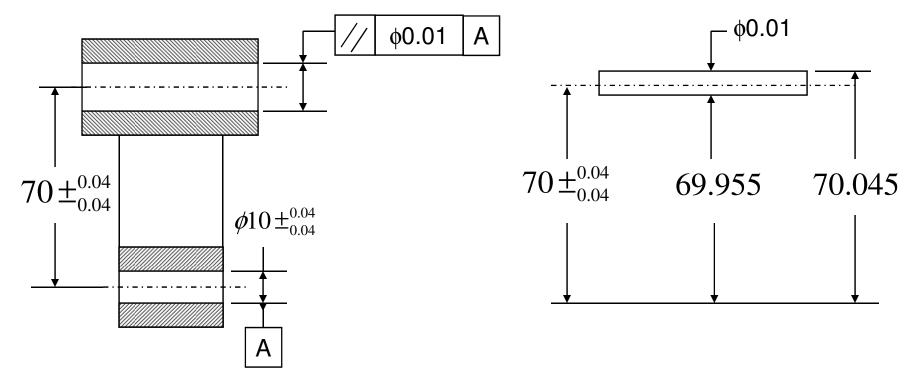
#### Parallelism

It is defined for a feature (like surface or line) with reference to another feature called reference. It defines the distance between two lines or surfaces that are parallel to each other and parallel to the datum surface and encompass the line or surface in question.

#### Parallelism of a Line with Line as datum



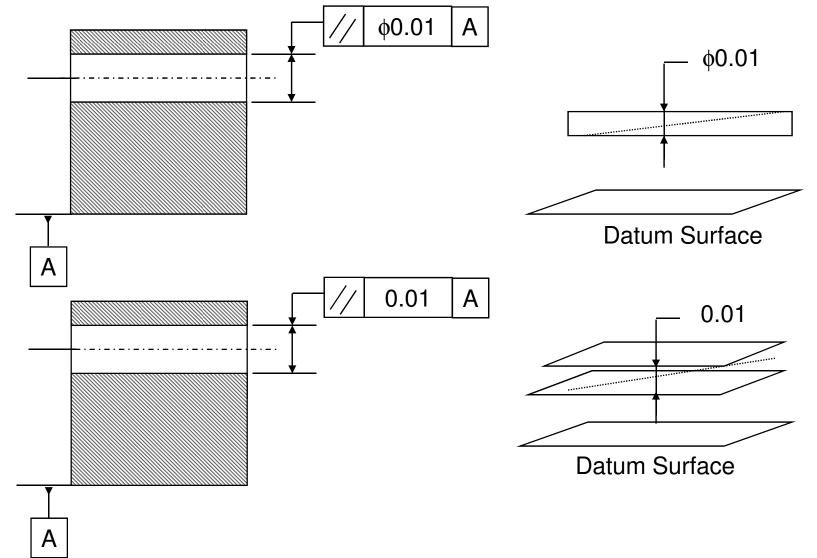
#### Parallelism of a Line with Line as a datum



Max. distance between holes = Max distance permitted by the dimensional tolerance (70.040) + (1/2) Geometrical tolerance (0.005) = 70.045 mm

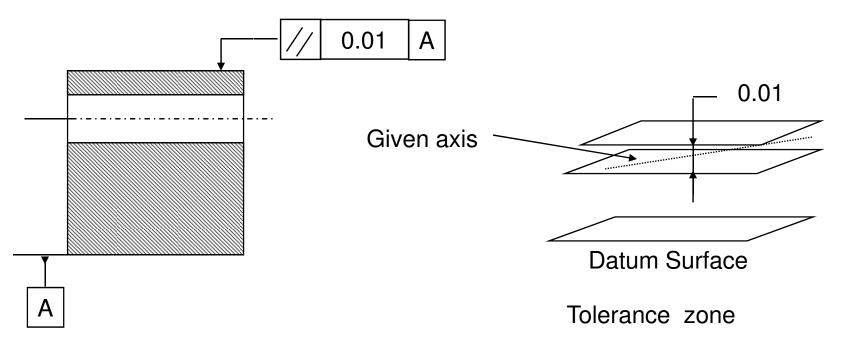
Min. distance between holes = Min. distance permitted by the dimensional tolerance (69.96) - (1/2) Geometrical tolerance (0.005) = 69.955 mm

#### Parallelism of a Line with Surface as a datum



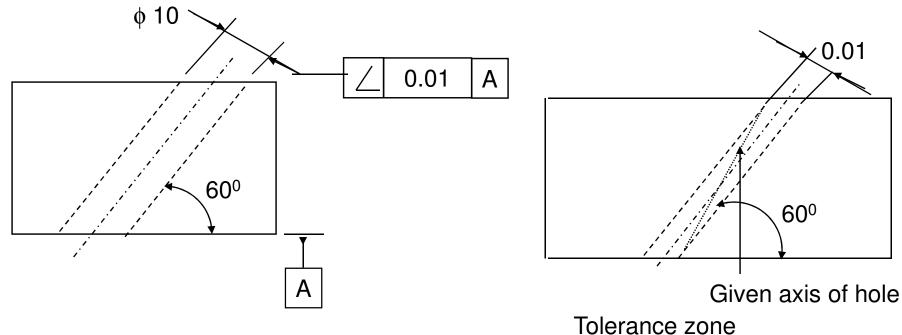
18

#### Parallelism of a Surface with Surface as a datum



#### Angularity

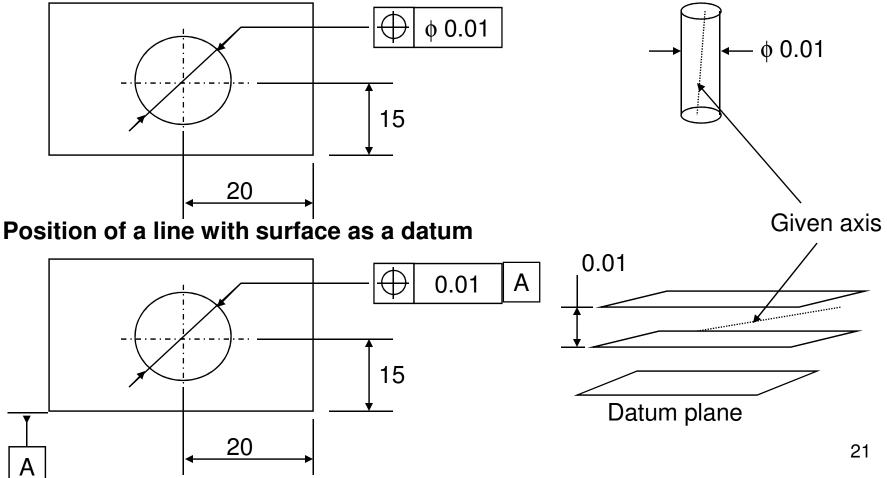
It is defined for a feature (like surface or line) with reference to another feature called reference. It defines the distance between two lines or surfaces that are at an angle to the datum surface and encompass the line or surface in question.



#### Position

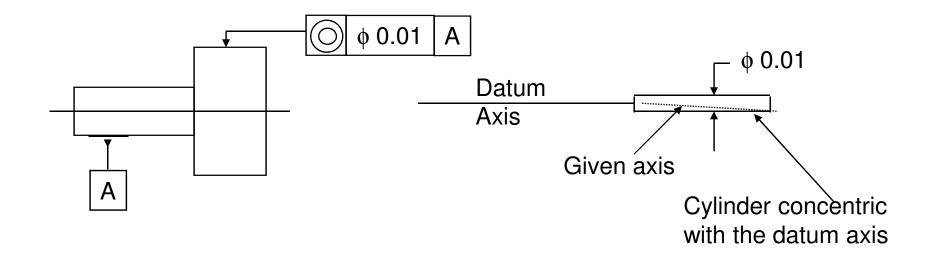
It defines the perfect (exact) location of a point, line or a surface in relation to the other datum

#### Position of a line



#### Concentricity

It defines the position of an axis in relation to the other datum axis. It defines a cylinder which coincides with the datum axis and of diameter given by the geometrical tolerance.



#### Run out

It defines the deviation from the desired form and orientation during one full rotation of the part on the datum axis.

